

CS Q-LEAP[™] SINE with SE-29 vibration calibration system with high frequency exciter

| | | \sim Typical DUT * | |
|------------|--|--|--|
| | HERO [™] vibration controller incl. signal conditioners | vibration sensors PE transducers IEPE transducers VC transducers PR transducers Digital transducers (SPI, I2C, DTI, and other interfaces) | |
| | CS Q-LEAP [™] software sine calibration sine sweep vibration measurement vibration generation more on demand | vibration meters vibration calibrators supports TEDS/ID modules according to IEEE 1451.4 DUT = Device Under Test | |
| La SPEKTRA | SE-29 high frequency vibration exciter with internal reference accelerometer and power amplifier | ISO 16063-21: Calibration of vibration transducers by comparison to a reference transducer ISO 16063-44: Calibration of field vibration calibrators ISO 17025: General requirements for the competence of testing and calibration laboratories | |

Key features

| | Vibration calibration system for the frequency range 3 Hz20 kHz |
|--------|--|
| | Traceable to PTB (German National Metrology Laboratory) |
| -0-111 | Calibration of vibration sensors, measurement systems and calibrators |
| | Integrated sensor database |
| | Integrated software for the generation of calibration certificates (print, PDF,) Easy data exchange with applications like ERP systems or measuring equipment databases |

🕄 Technical data

| Force rating, max. (sine peak) ¹⁾ | 95 N (21 lbf) | |
|--|---|--|
| Frequency range | 3 Hz 20 kHz - calibration mode (traceable) 20 kHz 50 kHz - extended range for testing purposes | |
| Acceleration, max. ¹⁾ | 450 m/s² (46 g _n) | |
| Displacement, max. (peak-peak) ²⁾ | 10 mm (0.39 in) | |
| DUT weight, max. | 2 kg (4.4 lbs) vertical 1 kg (2.2 lbs) horizontal | |

1) Interval mode of operation

2) Recommended operation range; mechanical stops at 12 mm (0.47 in)

| Frequency range | | Maximum recommended | Expanded measurement uncertainty ⁴⁾ |
|---|------------------------|--|--|
| from | to | payload for best performance ³⁾ | magnitude ⁵⁾ / phase ⁶⁾ of transfer coefficient |
| 5 Hz | < 10 Hz | 200 g (0.4 lbs) 0 | 1.0 % / 1.0° |
| 10 Hz | < 20 Hz | | 0.7 % / 0.7° |
| 20 Hz | 1 000 Hz | | 0.5 % / 0.7° |
| > 1 000 Hz | 5 000 Hz | 50 g (0.1 lbs) 50 g (0.1 lbs) 0.7 % / 0.7° 1.5 % / 1.0° 2.0 % / 2.0° 3.0 % / 3.0° | 0.7 % / 0.7° |
| > 5 000 Hz | 10 000 Hz | | 1.5 % / 1.0° |
| > 10 000 Hz | 15 000 Hz | | 2.0 % / 2.0° |
| > 15 000 Hz | 20 000 Hz | | 3.0 % / 3.0° |
| Reference frequencies: 80 Hz, 100 Hz, 160 Hz | | 200 g (0.4 lbs) | 0.5 % / 0.7° |
| Recommended e | xcitation amplitudes (| peak values) | |
| Minimum | | 1.0 m/s ² | |
| Maximum (high payload) ⁷⁾ (displacement, velocity, acceleration) | | 5 mm in the range 3 Hz12.5 Hz | |
| | | 0.4 m/s in the range 12.5 Hz48 Hz | |
| | | 120 m/s ² in the | e range 48 Hz1 kHz |
| | | | |

| | 350 m/s² in the range 5 kHz10 kHz |
|--|--|
| | 5 mm in the range 3 Hz12.5 Hz |
| Maximum (low payload) ⁸⁾ | 0.4 m/s in the range 12.5 Hz200 Hz |
| (displacement, velocity, acceleration) | 450 m/s ² in the range 200 Hz10 kHz |

190 m/s² in the range 1 kHz...5 kHz

3) Maximum recommended payload to comply the specfied measurement uncertainty for the system. Higher payloads are possible (according to the data sheet of vibration exciter), in this case individual estimations of the uncertainty must be performed.

4) Determined according to GUM (ISO Guide to the expression of uncertainty in measurement, 1995) with k = 2 (coverage factor) for the best possible DUT (other devices that are not as ideal have to be evaluated with individual additions)

5) Uncertainties only valid for electrical sensor signals \geq (1 mV or 1 pC)

6) Only in combination with optional extra PHASE

7) Maximum acceleration for maximum recommended payload of DUT

8) Maximum acceleration without any payload